

## まとめ I

### 参考文献

- [1] C. N. Yang and R. L. Mills, Phys. Rev. **96**, 191 (1954).
- [2] K. G. Wilson, Phys. Rev. D **10**, 2445 (1974).
- [3] 九後汰一郎, ゲージ場の量子論 I, II, 培風館
- [4] 山内恭彦・杉浦光夫, 連続群論入門, 培風館
- [5] H. Georgi, *Lie Algebras in Particle Physics*, Benjamin/Cummings, 1982

### Yang-Mills 場とカイラルフェルミオン

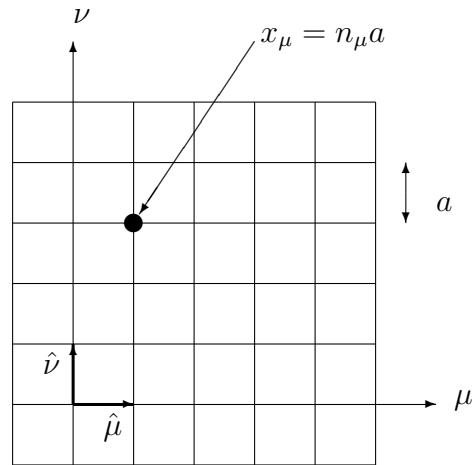
Target continuum theory :

$$\begin{aligned}\mathcal{L}(x) &= -\frac{1}{4}F_{\mu\nu}^a(x)F^{a\mu\nu}(x) + \sum_f \bar{\psi}(x) i\gamma_\mu(\partial_\mu + igA_\mu^a R_f[T^a])\psi(x) \\ F_{\mu\nu}^a(x) &= \partial_\mu A_\nu^a(x) - \partial_\nu A_\mu^a(x) + g f_{abc} A_\mu^b(x) A_\nu^c(x)\end{aligned}$$

### 格子理論

- 4-dim. Euclidean lattice  $\mathbb{L}^4 = \{x_\mu = n_\mu a \mid n_\mu \in \mathbb{Z}^4\}$ 
  - 場は格子点, または, Link  $(x, x + \hat{\mu})$  の上
  - Lorentz inv.  $\rightarrow$  hypercubic rotational inv.
- momentum cut-off  $p_\mu \in [-\frac{\pi}{a}, \frac{\pi}{a}]$
- Path-integral による量子化
  - Well-defined な Path-integral measure
  - 摂動論によらない regularization (cf. dimensional reg.)
  - Transfer-matrix  $\Rightarrow$  量子系の Hamiltonian
- 統計力学系 (スピン系) との対応
  - さまざま (非摂動的) 解析方法  
Weak, Strong coupling expansion, RG, MC simulation, …
  - 繰り込みの非摂動的な意味づけ

## 格子ゲージ理論



- Link variable: ベクトル場は Link  $(x, x + \hat{\mu})$  上に定義

$$U(x, \mu) = e^{iB_\mu(x)} \in G \quad (G = U(1), SU(N), \dots)$$

$$B_\mu(x) = ag T^a A_\mu^a(x)$$

- ゲージ変換

$$U(x, \mu) \longrightarrow g(x) U(x, \mu) g(x + \hat{\mu})^{-1}, \quad g(x) \in G$$

- Field strength

$$P(x, \mu, \nu) = U(x, \mu) U(x + \hat{\mu}, \nu) U(x + \hat{\nu}, \mu)^{-1} U(x, \nu)^{-1} \simeq \exp[ia^2 g F_{\mu\nu}(x) + \dots]$$

- Action:

$$S[U] = \beta \sum_{x, \mu, \nu} \frac{1}{2N} \text{ReTr}(1 - P(x, \mu, \nu)) \quad (\beta = 2N/g^2)$$

- Path-Integral measure:  $G$  上の不变測度  $d\mu(U) = d\mu(g_1 U) = d\mu(U g_2)$

$$Z = \int \prod_{x, \mu} dU(x, \mu) \exp(-S[U])$$

$$- \text{SU}(2) : U = a_0 \mathbb{I} + i \sum_{k=1}^3 a_k \sigma_k$$

$$dU = \frac{1}{2\pi^2} d^4 a \delta(a^2 - 1) = \frac{1}{2\pi^2} \sin^2 \psi \sin \theta d\psi d\theta d\phi$$

$$a_0 = \cos \psi$$

$$a_1 = \sin \psi \cos \theta$$

$$a_2 = \sin \psi \sin \theta \cos \phi$$

$$a_3 = \sin \psi \sin \theta \sin \phi$$